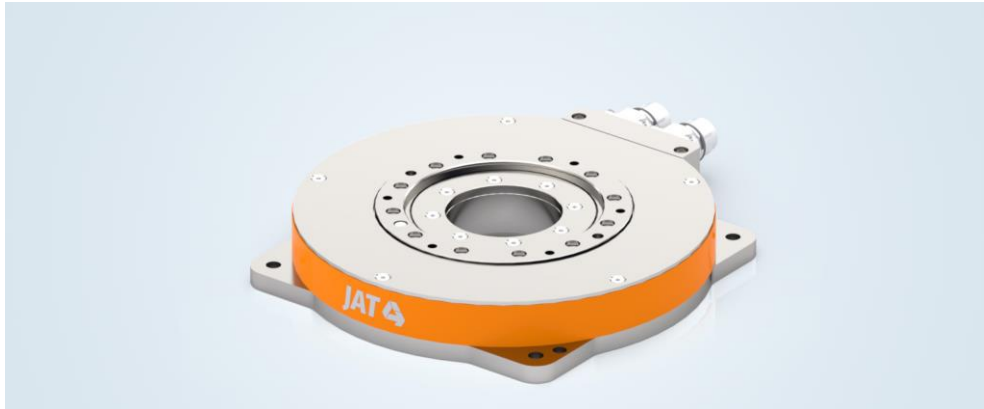


## Rotary Table System Series HRT-160

Innovative design for highest dynamic and precision



### Compact design

Example HRT-160-17: Ultra thin – build height 30 mm



### Highest torque density

Smaller packing means lowering footprint



### Low cogging value

Smooth motion and positioning accuracy



### No backlash

Highest stiffness



### Integrated measuring system

Incremental or absolute value encoder, different types

### Rotary table - ready to install

Mechanically & electrically ready for connection

M17 connectors

### Direct drive

Precise & no backlash

### Innovative design

Reduced moving mass for low inertia

### Low cogging value

Smooth running characteristics

### Customer specific modifications possible

### Use with servo amplifiers:

ECOVARIO® 414

ECOVARIO® 616(D)

### Field bus interfaces:

CANopen, EtherCAT, Profibus, Profinet, Ethernet, RS232, RS485

# Rotary Table System Series HRT-160

## → Technical data

		Series HRT-160-17	Series HRT-160-25	Series HRT-160-34	Series HRT-160-60
<b>Rated Values</b>				<b>(preliminary)</b>	<b>(preliminary)</b>
Max. rated DC link voltage	$V_{DC}$	325	325	325	560
Peak torque (c.d.f. 5%) <sup>1)</sup>	Nm	8,8	21,4	34,1	106,2
Maximum speed <sup>2)</sup>	min <sup>-1</sup>	500	500	500	t.b.d.
Rated torque <sup>1)</sup>	Nm	2,5	3,4	7,8	18,2
Max. current (per phase, c.d.f. 5%) <sup>1)</sup>	$I_{RMS}$	14	14	14	16
Rated current (per phase) <sup>1)</sup>	$I_{RMS}$	2,9	2,3	3,2	2,7
Repeatability <sup>2)</sup> with encoder incremental / absolute	arcsec	$\pm 3 / \pm 5 (\pm 2,5)^{5)}$	$\pm 3 / \pm 5 (\pm 2,5)^{5)}$	$\pm 3 / \pm 5 (\pm 2,5)^{5)}$	$\pm 3 / \pm 5 (\pm 2,5)^{5)}$
Radial eccentricity	standard	$\mu m$	< 25	< 35	t.b.d.
	optional	$\mu m$	< 10	< 10	t.b.d.
Axial eccentricity	standard	$\mu m$	< 25	< 35	t.b.d.
	optional	$\mu m$	< 10	< 10	t.b.d.

### Technical Data Motor

Torque constant	Nm/A	0,85	1,5	2,44	6,74
Voltage constant	V/1000 min <sup>-1</sup>	59,3	122,8	209	556
Winding resistance	$\Omega$	5,4	7,4	10,9	24,6
Winding inductivity	mH	8,9	14,2	30	95,8
Number of pole pairs	2p	18	18	18	18
Motor inertia	kgm <sup>2</sup> x10 <sup>-3</sup>	1,19	2,3	3,04	t.b.d.
Max. axial load	N	400 <sup>3)</sup>	750 <sup>3)</sup>	750 <sup>3)</sup>	t.b.d.
Max. radial load	N	250 <sup>3)</sup>	500 <sup>3)</sup>	500 <sup>3)</sup>	t.b.d.
Topple torque	Nm	10 <sup>4)</sup>	50 <sup>4)</sup>	50 <sup>4)</sup>	t.b.d.
Holding brake	Nm	-	2 (Option)	2 (Option)	2 (Option)

### Incremental Encoder

Resolution (standard) <sup>2)</sup>	inc/rev	532 000	532 000	532 000	532 000
Resolution (maximum) <sup>2)</sup>	inc/rev	1 945 600	1 945 000	1 945 000	1 945 000
Operating voltage	$V_{DC}$	5 ( $\pm 10\%$ )			
Signal specification		RS422			

### Absolute Value Encoder

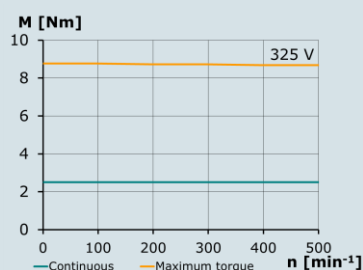
Resolution (standard)		18 Bit	18 Bit	18 Bit	18 Bit
Resolution (maximum) <sup>5)</sup>		21 Bit	21 Bit	21 Bit	21 Bit
Operating voltage	$V_{DC}$	5 ( $\pm 5\%$ )			
Protocol		BiSS C			

### Environmental Conditions

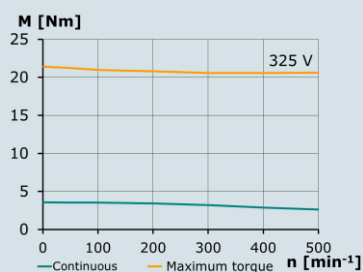
Ambient temperature		0 ... 40 °C			
Temperature switch-off sensor		PTC, 105 °C			
Protection class		IP40			

1. Mounting flange 250 mm x 250 mm / thickness 20 mm
2. Depends on the measuring system
3. speed: 300 min<sup>-1</sup>, a higher individual load leads to a limitation of the bearing life
4. speed: 300 min<sup>-1</sup> with maximum load, different application must be calculated
5. under preparation

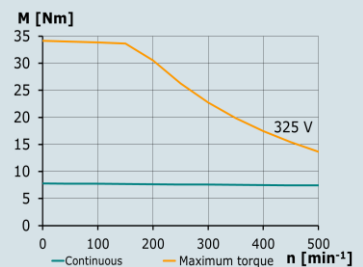
### Characteristic HRT-160-17/ECOVARIO® 414



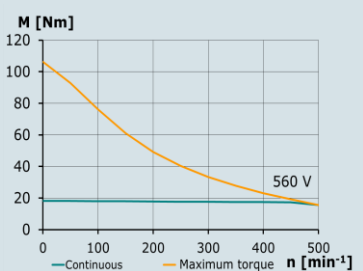
### Characteristic HRT-160-25/ECOVARIO® 414



### Characteristic HRT-160-34/ECOVARIO® 414



### Characteristic HRT-160-60/ECOVARIO® 616(D)



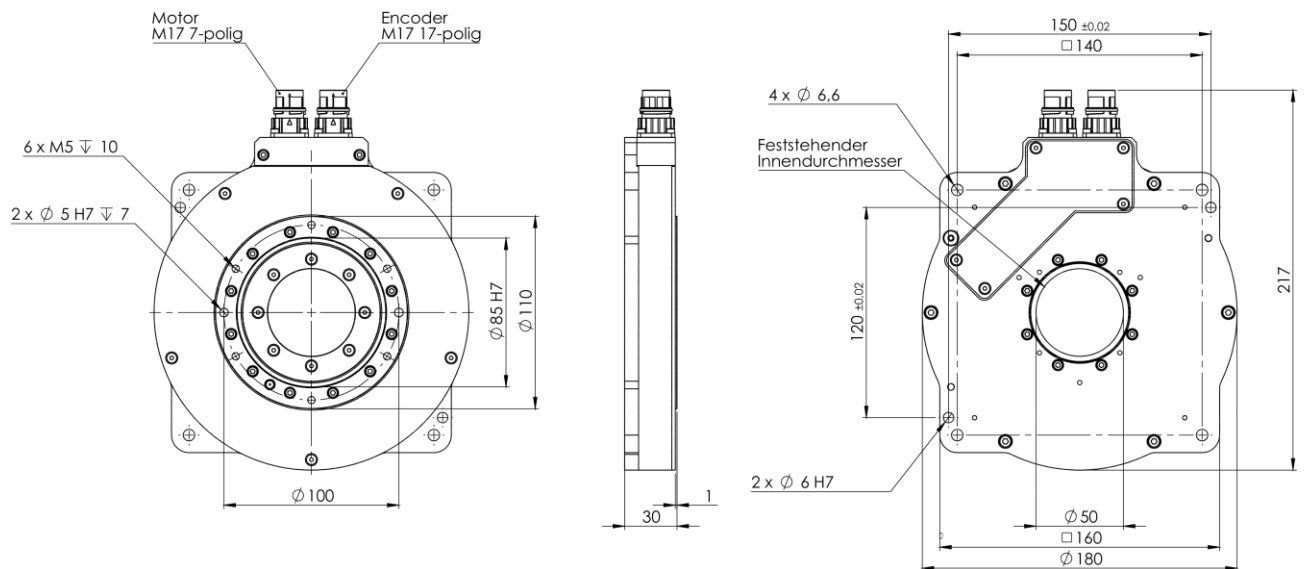
# Rotary Table System Series HRT-160

→ Dimensions

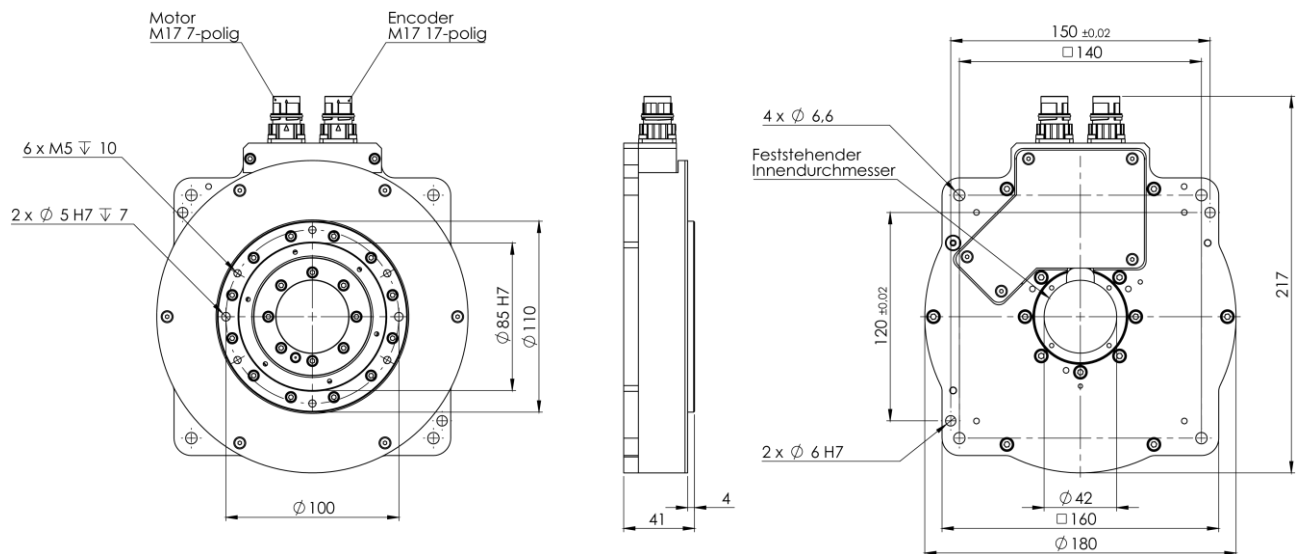
		Series HRT-160-17	Series HRT-160-25	Series HRT-160-34	Series HRT-160-60
Outer diameter	mm	180	180	180	180
Height	mm	30	41	50	t.b.d.
Weight without brake	kg	2,1 / 2,5*	3,2 / 3,6*	4,3 / 5,0*	t.b.d.
Weight with brake	kg	-	3,5 / 3,9*	4,6 / 5,3*	t.b.d.

\*) with option "Improved radial and axial run-out"

**HRT-160-17:**



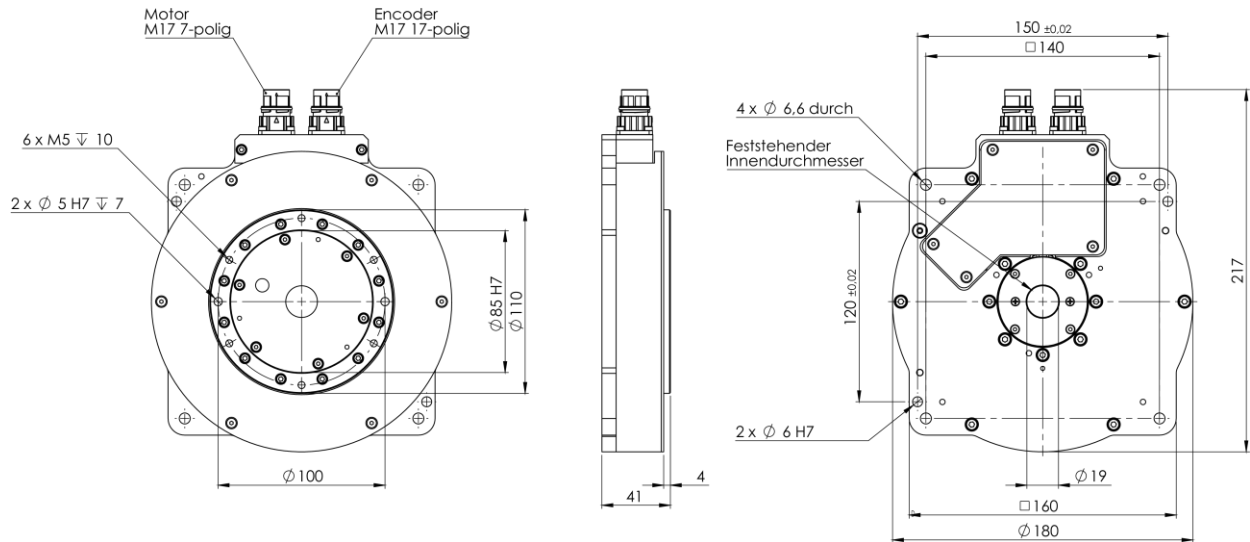
**HRT-160-25:**



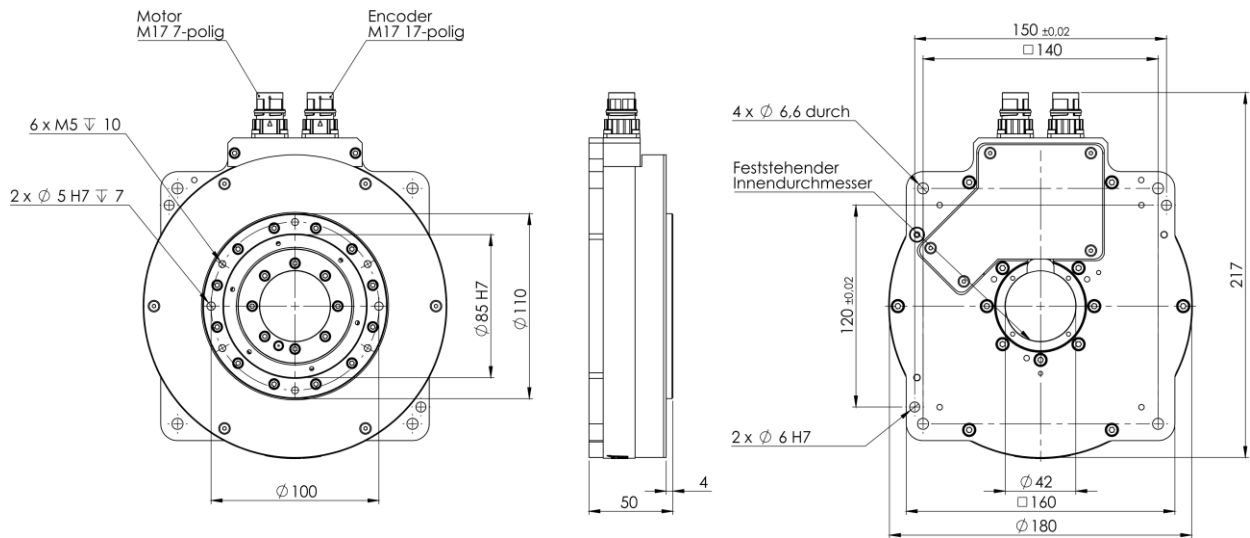
# Rotary Table System Series HRT-160

→ Dimensions

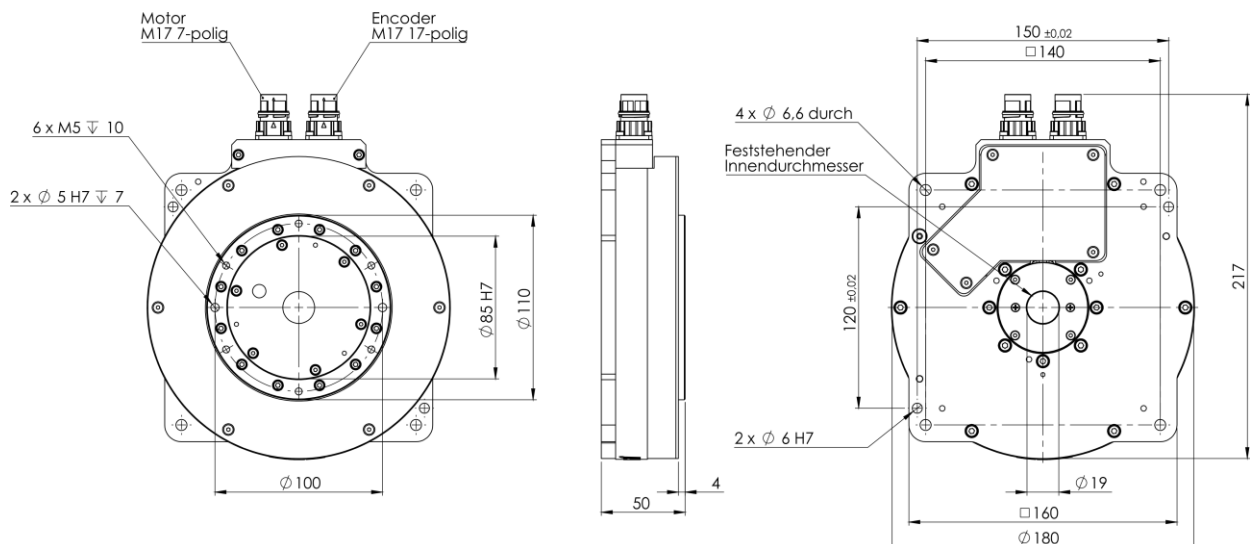
**HRT-160-25 with brake:**

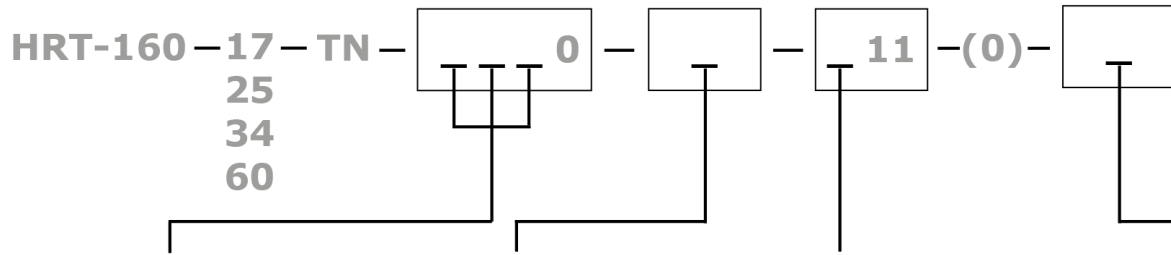


**HRT-160-34:**



**HRT-160-34 with brake:**





Measuring system	
500	Incremental 532 000 inc/rev
E04	Absolute 18 bit
E15	Absolute 21 bit *
*) under preparation	

Holding brake	
0	Without brake
7	Holding brake 2 Nm *
*) available for HRT-160-25, HRT-160-34 and HRT-160-60	

Connector outlet	
R	Radial (default)
A	Axial

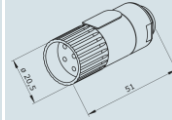
Option	
2	Default
4	Improved radial and axial run-out

# Rotary Table System Series HRT-160

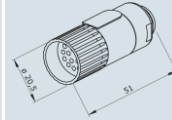
→ Accessories

Mating connector set 70.070 (for cables made by customer)

Motor mating connector M17



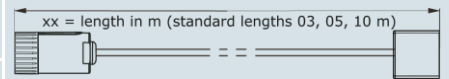
Encoder mating connector M17



Cable assemblies

Motor cable (for ECOVARIO® 414)  
MOT61-133-523-0xx-100

Ø 8,2 mm; trailing capability from bend radius > 80 mm



Motor cable (for ECOVARIO® 616)  
MOT67-133-523-0xx-100

Ø 8,2 mm; trailing capability from bend radius > 80 mm

Motor/brake cable (for ECOVARIO® 414)  
MOT63-134-523-0xx-100

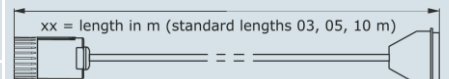
Ø 10,8 mm; trailing capability from bend radius > 105 mm

Motor/brake cable (for ECOVARIO® 616)  
MOT68-134-523-0xx-100

Ø ca. 10,8 mm; trailing capability from bend radius > 105 mm

Incremental encoder cable (ECOVARIO® 414)  
INK65-491-525-0xx-000

Ø 9,5 mm; trailing capability from bend radius > 90 mm



Incremental encoder cable (ECOVARIO® 616)  
INK65-305-525-0xx-000

Ø 9,5 mm; trailing capability from bend radius > 90 mm

Absolute encoder cable  
ABS65-300-525-0xx-000

Ø 9,5 mm; trailing capability from bend radius > 90 mm

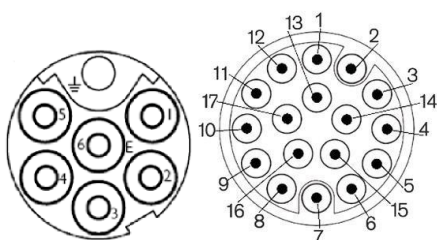
→ Connector and cable assignment

Assignment motor(/brake) cable

Connection	Motor connector pin M17	Motor (/brake) cable wire MOT61/63	Motor (/brake) cable wire MOT67/68
Phase U	4	3	1
Phase V	1	1	2
Phase W	5	4	3
Brake + (optional)	3	black (MOT63)	black (MOT68)
Brake - (optional)	6	white (MOT63)	white (MOT68)
PE	7	gn/ye	gn/ye
Shield	Housing	Shield	Shield

Motor connector:

Encoder connector:



Assignment incremental encoder cable

Connection	Encoder conn. pin	Encoder cable wire	Pin D-Sub 9 pin /HD 15 pins
+5V	15	brown	1
GND	16	white	6
Channel A	1	green	2
Channel /A	2	yellow	7
Channel B	3	grey	3
Channel /B	4	pink	8
Channel N	5	blue	4
Channel /N	6	red	9
PTC	7	violet	5
PTC	8	black	6 / 10
Shield*	Housing	bare	Shroud

Assignment absolute encoder cable

Connection	Encoder conn. pin	Encoder cable wire	Pin D-Sub HD (15 pins)
+Up	13	brown	1
GND	16	white	6
Channel CLK	11	green	14
Channel /CLK	12	yellow	15
Sens S-	17	grey	11
Sens S+	14	pink	12
Channel DAT	9	blue	4
Channel /DAT	10	red	9
PTC	7	violet	5
PTC	8	black	10
Shield	Housing	bare	Shroud

\*) D-Sub HD 15 pins: additional bridges in connector, double shielding